

The controller tracking the set point of 80 mg/decilitre level and then the meal disturbance with magnitude of 3.33g/minute is applied at 400th minute as a pulse which raises the glucose level of patient. The GA-IMC based controller rejects the meal disturbance effectively than GA-PID control. The GA-IMC regulates the glucose level within 40 minutes after having meal whereas GA-PD takes longer time to regulate the glucose level.

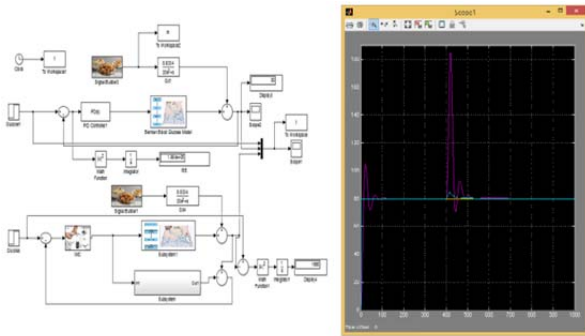


Figure 4 simulation of closed loop GA-PD, GA-IMC controller for blood glucose system

The optimised control value for minimum ISE is tabulated for GA-PD and GA-IMC in table 1,2.

Table.1 GA-PD Controller

	kp	ki	ISE
GA-PD	-0.0527	-2.37	1666

Table.2 GA-IMC controller

	λ	ISE
GA-IMC	-0.12	45810

The blood glucose level has to maintain a particular level while it increases, naturally pancreas inject the insulin to our body to maintain the glucose level whereas for type-1 diabetic patients pancreas doesn't inject the insulin so insulin pump injects the insulin. The glucose sensor continuously monitoring the blood glucose level after a meal the glucose level is increases drastically it has refers to input disturbances to the process. The Process is first order with dead time process. The genetic algorithm based single loop PD controller is used for control the blood glucose system. Insulin pump there is a stepper motor it coupled with a injection needle shaft. If the glucose level increases the ID controller produces a control signal in terms of voltage to drive a stepper motor. The displacement of shaft is equivalent to injection of insulin into human body. The PD controller tuned using GA to achieve minimum ISE. The PD control signal affects the insulin system due to its oscillatory response; the time take to regulate the blood glucose is high. To overcome this complexity genetic algorithm based (GA) IMC controller is used.

In practice, the glucose level does not enter the blood stream immediately. Meals take some time to reach it into blood stream. Assume, the patient is taking 50g meal over 15 minutes. Hence 3.3g/minutes pulse is applied in simulation for 15 minutes. The glucose level increases

suddenly due to the meal, and it is gradually reduced by applying insulin.

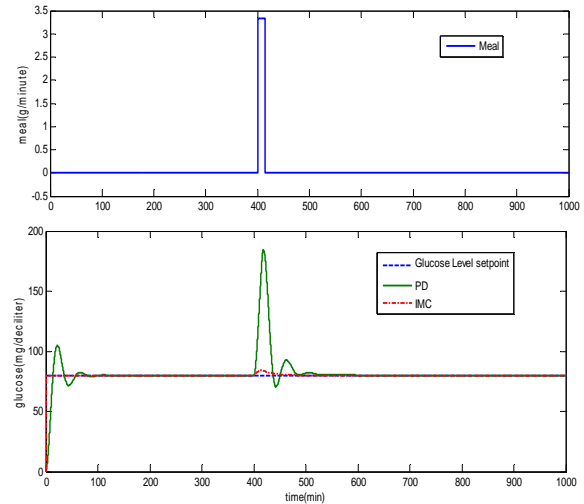


Figure 5 Comparison of GA-PD response, GA-IMC response to meal disturbance

6. CONCLUSION:

In this paper GA based PD controller proposed for blood glucose system. The simulation part was done by taking Bergmann's minimal model as a reference model from which glucose and insulin kinetics were referred and then it is simulated. In the simulation, Glucose (meal) is taken as a disturbance which has to be controlled by infusing the insulin in blood of the patient which maintains the glucose level in blood as normal. It is inferred that GA-IMC and GA-PD controllers are compared. The superiority of GA-IMC is shown and discussed. The optimal selection of filter constant in IMC regulates the blood glucose level effectively.

There is major research effort to develop implantable glucose sensors and insulin pumps. The IMC is a model based control which requires exact model of blood glucose system, but the modelling varies patient to patient. The modelling has to be done for each patient using his glucose level data.

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